

Automation and growth

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Automation growth and the labor market

- ▶ There is a reduction in the labor share of income in several countries **Ex. US** also in **Europe** (see page 10)
- ▶ There is also an increase in the number of robots **particularly in Asia** in all **industries**
- ▶ Are the two processes related ?

Robots and machines

- ▶ Robots have a peculiar nature:
 - ▶ they are generated by a production process similar to machines
 - ▶ they are financed in a similar way as machines
 - ▶ but they are more substitutable to labor than to machines
- ▶ Next we show that the inclusion of robots can generate endogenous growth in a Ramsey-like model
- ▶ And, potentially, a permanent reduction in the labor share in GDP

The macroeconomic constraint

- ▶ Assumption:
 - ▶ machines are Edgeworth complements to labor and robots
 - ▶ labor and robots are Edgeworth substitutes
- ▶ The production function

$$Y = M^\alpha \left(A_n N + L \right)^{1-\alpha}, \quad 0 < \alpha < 1$$

where Y = output, M = input of machines, N = input of robots, and L = labour input, A_n is the specific productivity of robots

The macroeconomic constraint

- ▶ Assumption: savings are proportionally allocated to investment in machines, θ , and to robots $1 - \theta$
 - ▶ Distribution of savings to machines

$$\theta S = \dot{M} + \delta M$$

δ = depreciation rate

- ▶ Distribution of savings to robots

$$(1 - \theta) S = \dot{N} + \delta N$$

- ▶ Then

$$S = \dot{N} + \delta N + \theta S = \dot{M} + \dot{N} + \delta(M + N) = \dot{K} + \delta K$$

where the stock of capital is

$$K \equiv M + N$$

The macroeconomic constraint

- ▶ Equilibrium in the good's market

$$Y = C + S \iff Y = C + \dot{K} + \delta K$$

- ▶ Assumption: zero population growth

$$\dot{L} = 0$$

The macroeconomic constraint

- ▶ Capital intensity

$$k(t) \equiv \frac{K(t)}{L(t)}$$

- ▶ Fraction of machines in the total capital stock

$$\mu \equiv \frac{M}{K} \in [0, 1]$$

- ▶ The equilibrium condition is equivalent to

$$\dot{k} = (\mu k)^\alpha \left(A_n (1 - \mu) k + 1 \right)^{1-\alpha} - c - \delta k$$

where $c \equiv C/L$ (per-capita consumption)

A Ramsey problem: efficient capital accumulation

Find the consumption and capital allocation between machines and robots to solve

$$\begin{aligned} & \max_{c(\cdot), \mu(\cdot)} \int_0^{\infty} \ln(c(t)) e^{-\rho t} dt, \quad \rho > 0 \\ & \text{subject to} \\ & \dot{k} = y(\mu, k) - c - \delta k \\ & 0 \leq \mu(t) \leq 1 \\ & k(0) = k_0 \text{ given} \\ & \lim_{t \rightarrow \infty} e^{-\rho t} k(t) \geq 0 \end{aligned} \tag{P1}$$

where per-capita output is

$$y(\mu, k) = (\mu k)^\alpha \left(A_n (1 - \mu) k + 1 \right)^{1-\alpha}$$

The optimal share of machines in capital

- ▶ the optimal share of machines depends on the level of the capital stock

$$\mu^* = \begin{cases} 1 & \text{if } 0 < k \leq k_m \\ \frac{\alpha(1 + A_n k)}{A_n k} & \text{if } k > k_m \end{cases}$$

where

$$k_m \equiv \frac{1}{A_n} \left(\frac{\alpha}{1 - \alpha} \right).$$

- ▶ there are two regimes: no automation (for low level of capital) and automation (for higher level of capital)

The optimal share of machines in capital

Proof:

- ▶ The Hamiltonian is

$$H(c, \mu, k, q) = \ln c + q (y(k, \mu) - c - \delta k)$$

subject to the constraint $0 \leq \mu \leq 1$

- ▶ The optimality condition for μ , assuming that it has no constraint, is

$$q \frac{\partial y}{\partial \mu} = 0$$

where

$$\frac{\partial y}{\partial \mu} = \frac{y}{\mu} \left(\frac{A_n (\alpha - \mu) k + \alpha}{A_n (1 - \mu) k + 1} \right)$$

- ▶ Then, because $q > 0$ it holds if and only if

$$\mu = \alpha \left(1 + \frac{1}{A_n k} \right)$$

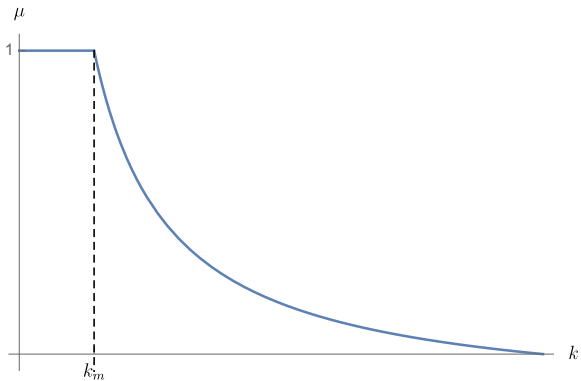


Figure: The optimal capital allocation function $\mu^*(k)$ where $M = \mu^* K$

The optimal share of machines in capital

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- ▶ Then, because $q > 0$ it holds if and only if

$$\mu = \alpha \left(1 + \frac{1}{A_n k} \right) > 0$$

as we see $\mu'(k) < 0$ the proportion of machines (robots) in capital decreases (increases) with k

The optimal share of machines in capital

Proof (cont.):

- ▶ $\mu = 1$ if and only if $k = \alpha / (A_n \cdot (1 - \alpha)) = k_m$
- ▶ therefore
 - ▶ $\mu \leq 1$ (non-binding constraint) if and only if $k \geq k_m$
 - ▶ $\mu = 1$ (binding if $k < k_m$)

Two regimes

- ▶ **There are two regimes**
 - ▶ For low levels of capital there are no robots
 - ▶ For higher levels of capital there robots
- ▶ Optimal output in the two regimes (no robots, with robots)

$$Y(k) = \begin{cases} k^\alpha & \text{if } 0 < k \leq k_m \\ \phi(A_n) (A_n k + 1) & \text{if } k > k_m \end{cases} \quad (1)$$

where $\phi(A_n) \equiv A_n^{-\alpha} \alpha^\alpha (1 - \alpha)^{1-\alpha}$

- ▶ Proof: for $\mu = 1$ it is easy, but for $0 < \mu < 1$ we have

$$\begin{aligned} y &= (\mu k)^\alpha \left(A_n (1 - \mu) k + 1 \right)^{1-\alpha} \\ &= \left(\alpha \left(\frac{1 + A_n k}{A_n} \right) \right)^\alpha \left(A_n (1 - \alpha) k - \alpha + 1 \right)^{1-\alpha} \\ &= \alpha^\alpha (1 - \alpha)^{1-\alpha} \left(1 + A_n k \right) \end{aligned}$$

Two regimes

- ▶ Rate of return for the two regimes

$$R(k) = \begin{cases} \alpha k^{\alpha-1} & \text{if } 0 < k \leq k_m \\ \tilde{r} & \text{if } k > k_m \end{cases} \quad (2)$$

where

$$\tilde{r} = A_n \phi(A_n) = A_n^{1-\alpha} \alpha^\alpha (1-\alpha)^{1-\alpha}.$$

- ▶ Proof: in $R(k) = \frac{\partial y(k, \mu)}{\partial k}$, where

$$\frac{\partial y(k, \mu)}{\partial k} = \frac{y}{k} \left(\frac{\alpha + A_n (1-\mu) k}{1 + A_n (1-\mu) k} \right)$$

we make the same substitutions as for the production functions

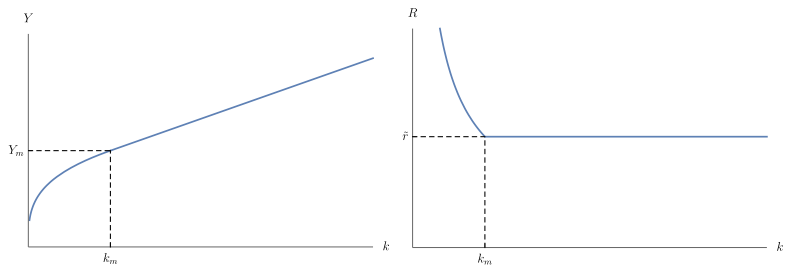


Figure: The optimal output and real return functions $Y(k)$ and $R(k)$.

The optimum dynamics

- ▶ The optimum path $(k(t), c(t))_{t \in [0, \infty)}$ is the solution of

$$\left\{ \begin{array}{l} \dot{k} = Y(k) - c - \delta k \\ \dot{c} = c(R(k) - (\rho + \delta)) \\ k(0) = k_0 \\ \lim_{t \rightarrow \infty} \frac{k(t)}{c(t)} e^{-\rho t} = 0 \end{array} \right. \quad (\text{MHDS})$$

- ▶ where $k(t)$ and $c(t)$ are level variables.

Steady state

There is a critical value for productivity

$$A_n^* \equiv \left(\frac{\rho + \delta}{\alpha^\alpha (1 - \alpha)^{1-\alpha}} \right)^{\frac{1}{1-\alpha}} \quad (3)$$

1. if $A_n < A_n^*$ then there is one steady state (k^*, c^*) such that $k^* < k_m$;
2. if $A_n = A_n^*$ then there is a steady state (k_m, c^*) ;
3. if $A_n > A_n^*$ then there are no steady states

No automation steady state

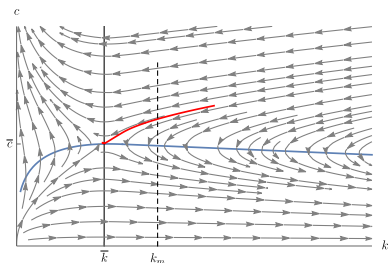


Figure: Phase diagram for $A_n < A_n^*$.

- ▶ if $A_n < A_n^*$ (high costs in using robots)
- ▶ there is no long run growth (Ramsey case)

Automation

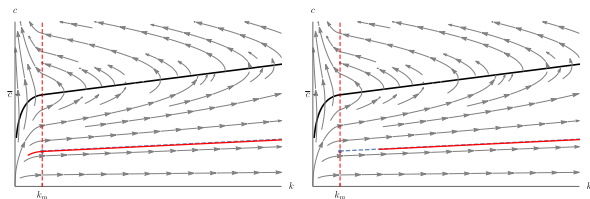


Figure: Phase diagram for $A_n > A_n^*$ starting in region 1 and 2.

- ▶ if $A_n > A_n^*$ (high costs in using robots)
- ▶ there is long run growth (as in the AK model)
- ▶ independently of the level of k_0
- ▶ the long-run growth rate is for $u(c) = \ln(c)$

$$\gamma = \tilde{r}(A_n) - \rho - \delta$$

Modified AK case

- ▶ Assume that $A_n > A_n^*$ and $k_0 > k_m$
- ▶ Solving the problem (MHDS) we obtain the solution for the capital stock

$$k(t) = k_0 e^{\gamma t} + \frac{\phi(A_n)}{\rho + \gamma} (e^{\gamma t} - 1)$$

- ▶ Exercise: prove this
- ▶ Therefore, if $\gamma > 0$ then

$$\lim_{t \rightarrow \infty} k(t) = \infty$$

The share of labor in national income

- ▶ The share of labor in the GDP is

$$\omega = \frac{WL}{Y} = \frac{\partial Y}{\partial L} \frac{L}{Y} = \frac{1 - \alpha}{A_n (1 - \mu) k + 1}$$

where W is the wage rate

- ▶ In the optimum, if $0 < \mu(k) < 1$ it becomes

$$\omega(t) = \frac{1}{1 + A_n k(t)}$$

- ▶ Therefore, as $\lim_{t \rightarrow \infty} k(t) = \infty$ then the share of labor in national income converges to zero **asymptotically**

$$\lim_{t \rightarrow \infty} \omega(t) = 0$$

(under the previous conditions: $A_n > A_n^*$ and $k_0 > k_m$)

Final remarks

- ▶ Although this model refers to robots, it is more general.
- ▶ It shows a potential emergence of endogenous growth from a Ramsey type model.
- ▶ Possibly, industrial revolutions start by introducing tools that are substitutable with labor, at least in a first phase.
- ▶ Although it is a simple model it raises the question: does the reduction of the labor share is a permanent consequence of automation ?

Final remarks

- ▶ Off course, there will be other mechanisms that would avoid this type of development:
- ▶ For instance if we introduce high-skill labor which would be complementary with machines and robots, will this result old ?
- ▶ Is this result dependent upon the particular production function we have introduced ? Even if we assume that robots and labor are substitutable ?